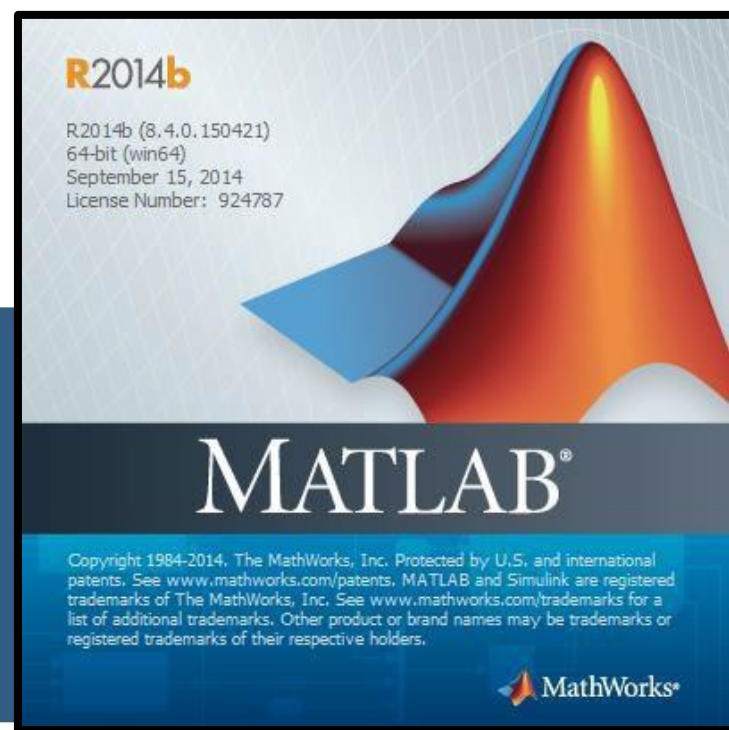




 POLITECNICO DI MILANO



Esercitazione 9

Corso di Strumentazione e Controllo di impianti chimici

Prof. Davide Manca

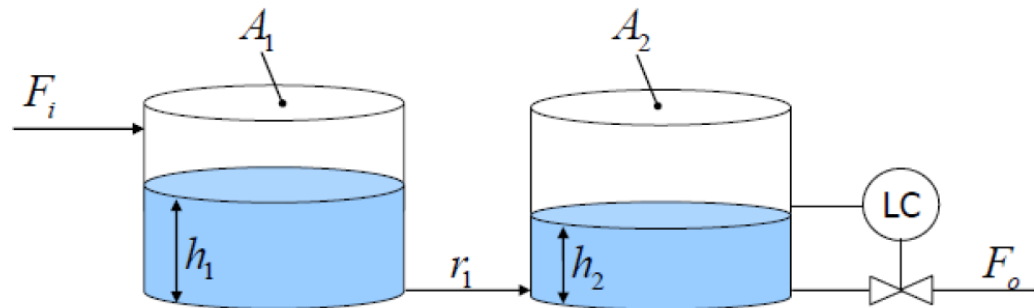
PSE-Lab



Esercitazione 9

Dati

$$F_i = 9.4 \frac{m^3}{s} \quad A_1 = 30 m^2 \quad A_2 = 50 m^2$$
$$R_1 = 1.2 \frac{s}{m^2} \quad h_0 = 3 m \quad C_d = 1.43$$

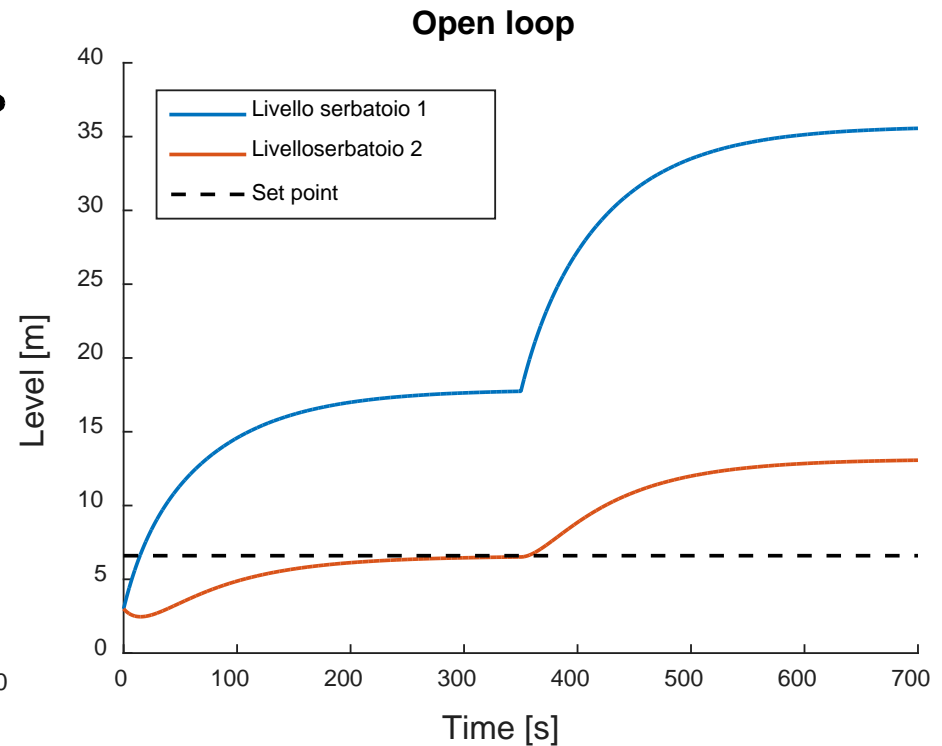
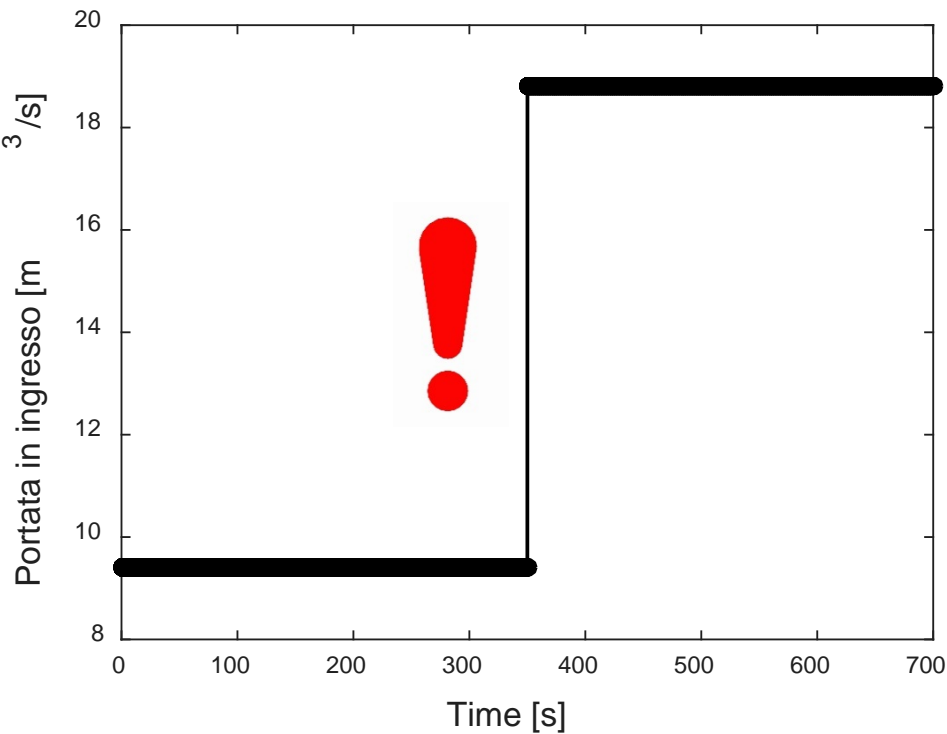




Anello aperto



Come reagisce il sistema al disturbo a gradino (in assenza di controllore)?

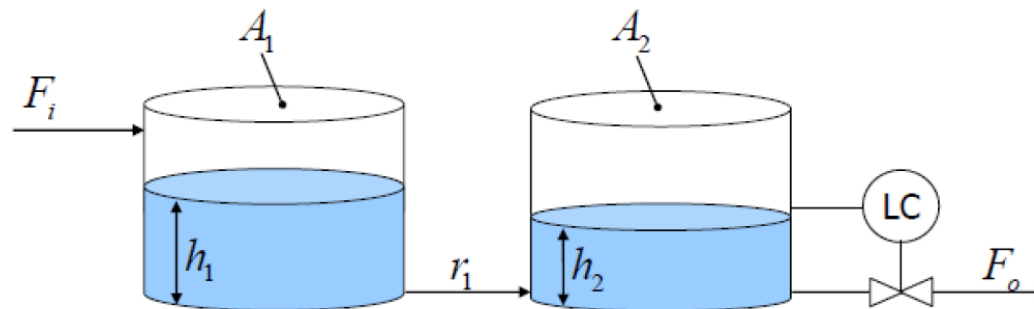




Caratteristiche del closed-loop:

- Variabile Controllata = Livello
- Variabile Manipolata = Portata uscente dal 2° serbatoio

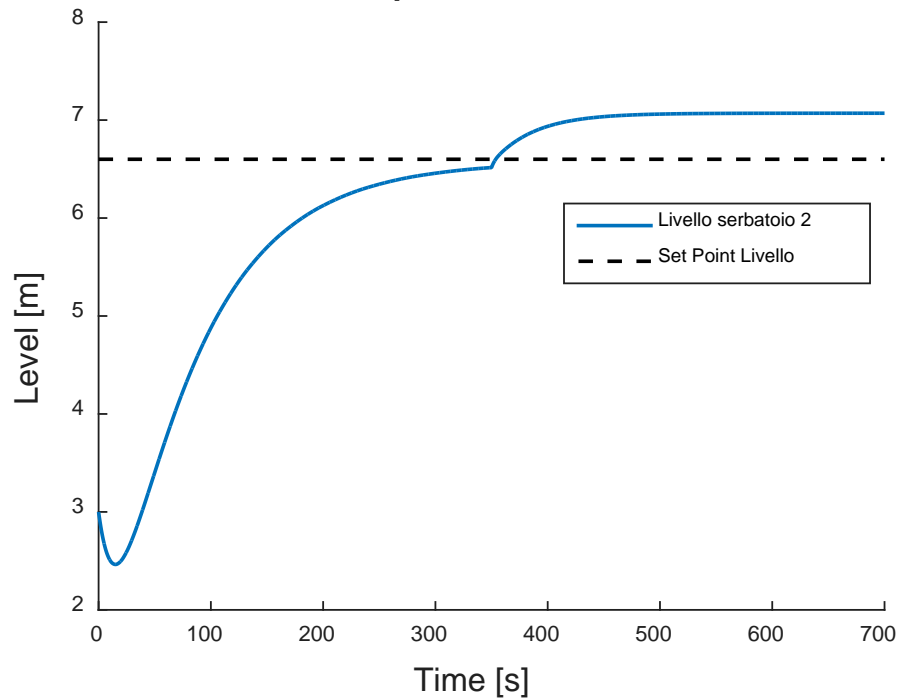
$$y_{set\ point} = 6.6\ m$$





Qual è l'effetto del controllore di tipo proporzionale?

Closed loop - P controller



Final offset: $\varepsilon > 0$



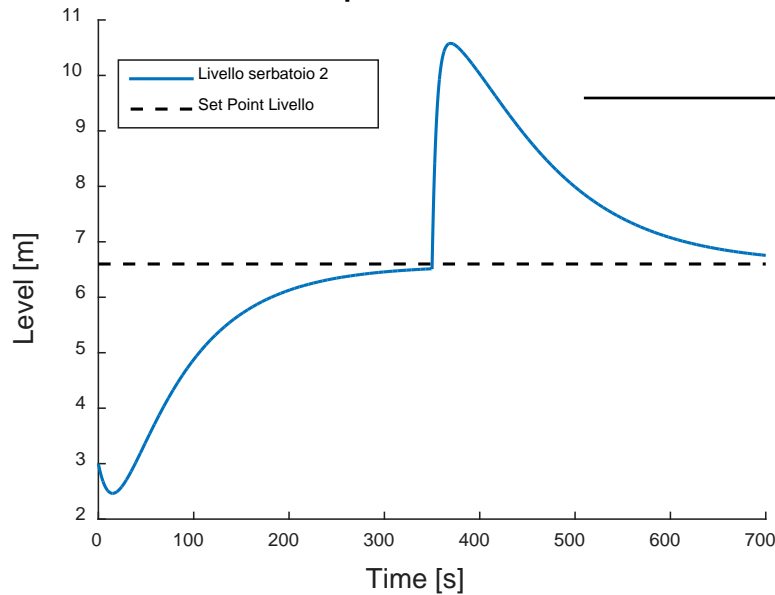
Legge di controllo:

$$c(t) = c_s + k_c \cdot \varepsilon$$



Qual è l'effetto del controllore di tipo proporzionale-integrale?

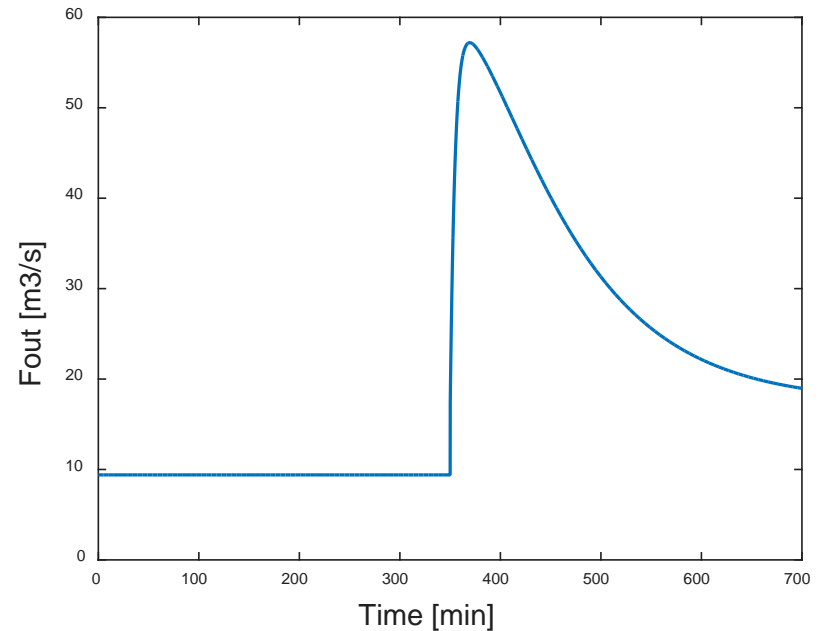
Closed loop - PI controller



Presenza di un «overshoot»



Variabile manipolata

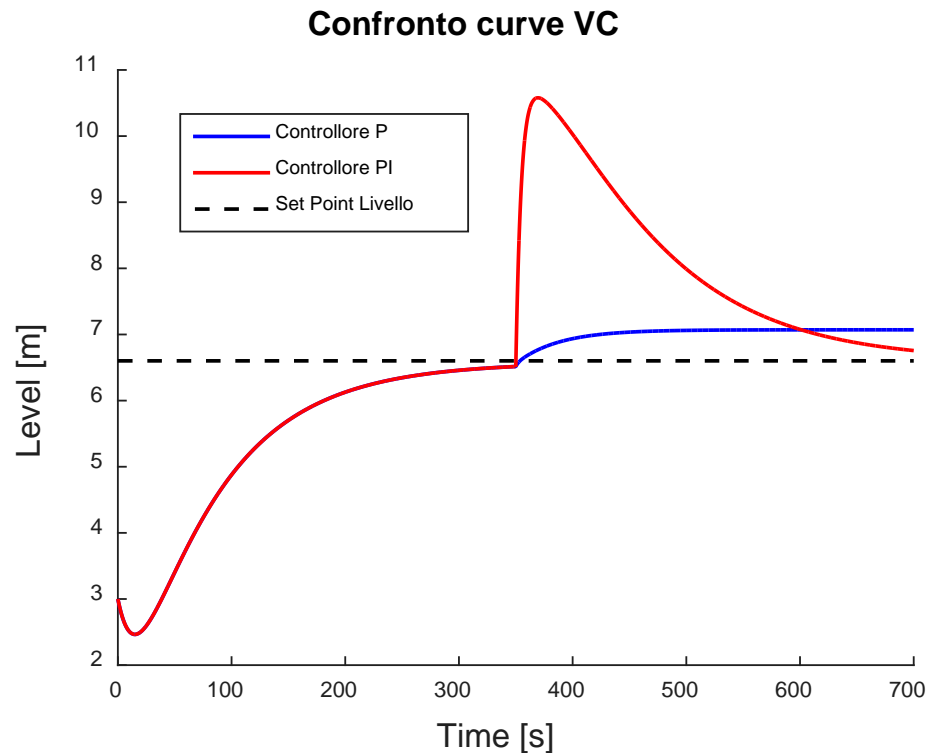


Legge di controllo:

$$c(t) = c_s + k_c \cdot \varepsilon + k_c \cdot \int \varepsilon dt$$



Effetto Azione P vs PI



Azione proporzionale:

- Garantisce PRONTEZZA della risposta
- Non garantisce PRECISIONE DELLA REGOLAZIONE

Azione proporzionale - integrale:

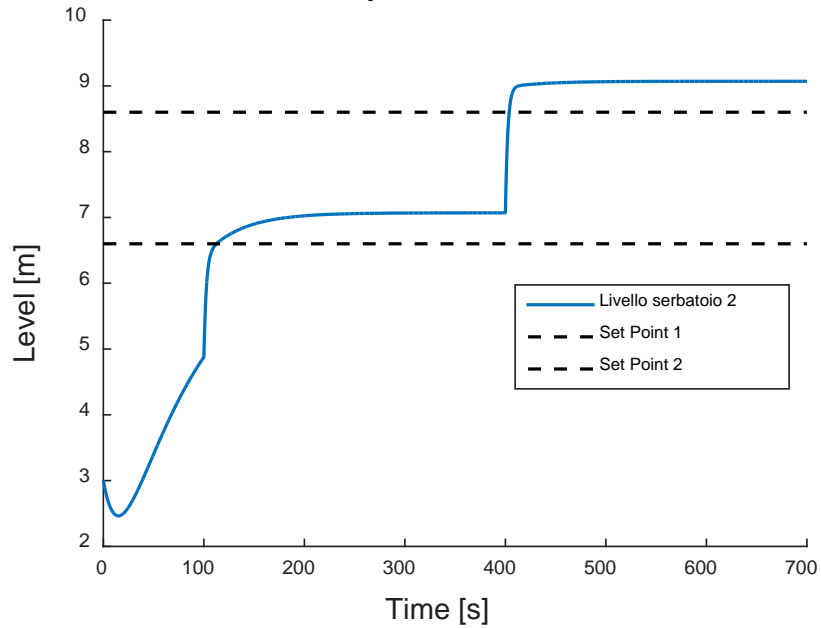
- Garantisce PRECISIONE DELLA REGOLAZIONE
- All'aumento del rapporto K_c/τ_I aumenta la velocità
 - L'ordine della risposta è aumentato



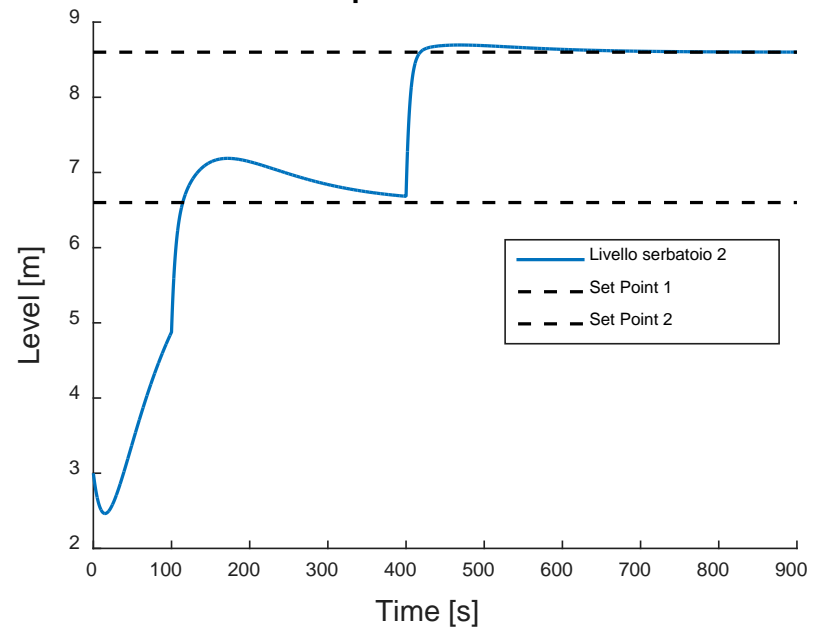
Cambio Set point



Closed loop - P controller



Closed loop - PI controller





How to



```
function Ese_9
clc
close all
clear all
global R1 A1 A2 livelloSetPoint Kc tDisturbo coeffScarico h0 tau_
    % Data
    % Serbatoio 1
    A1 = 30.; % [m2] area serbatoio 1
    A2 = 50.; % [m2] area serbatoio 2
    R1 = 1.2; % [s/m2] resistenza al flusso -> Fout = (h1-h2)/r
    Fin = 9.4; % [m3/s]
    h0 = 3.; % [m] livello iniziale nei due serbatoi

    % Serbatoio 2
    coeffScarico = 1.43; % [m2/s] La legge prevede: Fo =
1.43*h2
    livelloSetPoint = 6.6; % [m]
    tDisturbo = 350.; %[s] tempo al qual introduco il disturbo a
gradino sulla portata IN Fin
```



How to



```
% Comando OPEN LOOP
```

```
tspan = [0:0.1:700];
```

```
[t,L] = ode23s(@ODELivelloSerbatoi,tspan,[h0 h0]);
```

```
for i = 1: length(t)
```

```
    LivelloSetPoint(i) = livelloSetPoint;
```

```
end
```

```
figure(1)
```

```
hold on
```

```
title('Open loop','FontSize',18)
```

```
set(gca,'fontsize',13)
```

```
plot(t,L(:,1),'LineWidth',1.5)
```

```
plot(t,L(:,2),'LineWidth',1.5)
```

```
plot(t,LivelloSetPoint,'k--','LineWidth',1.5)
```

```
xlabel('Time [s]','FontSize',18)
```

```
ylabel('Level [m]','FontSize',18)
```

```
legend('Livello serbatoio 1','Livelloserbatoio 2','Set point')
```

```
xlim([0 tspan(length(tspan))])
```



How to



```
% Grafico portata IN
indexDisturbo = find(t >=tDisturbo);
for i = 1:length(tspan)
    if i <= indexDisturbo(1)
        Fin(i) = 9.4;
    else
        Fin(i) = 9.4*2;
    end
end

figure(5)
title('Disturbo a gradino','FontSize',18)
plot(tspan,Fin,'Color','k','Marker','o','LineWidth',1.5)
xlabel('Time [s]','FontSize',18)
ylabel('Portata in ingresso [m^3/s]','FontSize',18)
xlim([0 700])
set(gca,'fontsize',13)
```



How to



```
% Comando Controllore P
```

```
Kc = 20;
```

```
tspan = [0 :0.1: 700];
```

```
[t1,L1] = ode23s(@ODELivelloSerbatoioControlloP,tspan,[h0 h0]);
```

```
for i = 1: length(t1)
```

```
    LivelloSetPoint(i) = livelloSetPoint;
```

```
end
```

```
figure(2)
```

```
hold on
```

```
set(gca,'fontsize',12)
```

```
title('Closed loop - P controller','FontSize',18)
```

```
plot(t1,L1(:,2),'LineWidth',1.5)
```

```
plot(t1,LivelloSetPoint,'k--','LineWidth',1.5)
```

```
xlabel('Time [s]','FontSize',18)
```

```
ylabel('Level [m]','FontSize',18)
```

```
legend('Livello serbatoio 2','Set Point Livello')
```

```
xlim([0 tspan(length(tspan))])
```



How to



```
% Comando Controllore PI
```

```
Kc = 10;
```

```
tau_I = 100;
```

```
tspan = [0 :0.1: 700];
```

```
[t2,L2] =
```

```
ode23s(@ODELivelloSerbatoioControlloPI,tspan,[h0 h0 0]);
```

```
for i = 1: length(t1)
```

```
    LivelloSetPoint(i) = livelloSetPoint;
```

```
end
```

```
    figure(3)
```

```
hold on
```

```
set(gca,'fontsize',12)
```

```
title('Closed loop - PI controller','FontSize',18)
```

```
plot(t2,L2(:,2),'LineWidth',1.5)
```

```
plot(t2,LivelloSetPoint,'k--','LineWidth',1.5)
```

```
xlabel('Time [s]','FontSize',18)
```

```
ylabel('Level [m]','FontSize',18)
```

```
legend('Livello serbatoio 2','Set Point Livello')
```

```
xlim([0 tspan(length(tspan))])
```



How to



```
% Grafico PORTATA Fout
```

```
indexDisturbo = find(t2 >= tDisturbo);  
    for i = 1: length(t2)  
        epsi(i) = + L2(i,2) - livelloSetPoint;  
        if i <= indexDisturbo(1)  
            Fout(i) = 9.4;  
        else  
            Fout(i) = 9.4 + Kc * epsi(i) +  
Kc / tau_I * L2(length(L2(:,3)),3);  
        end  
    end  
end
```

```
figure(10)  
plot(t2,Fout, 'LineWidth',1.5)  
xlabel('Time [min]', 'FontSize',18)  
ylabel('Fout [m3/s]', 'FontSize',18)
```

```
end % chiudo la function Ese_9
```



How to



```
function dy = ODELivelloSerbatoi(t,y)

    global R1 A1 A2 livelloSetPoint Kc tDisturbo
    coeffScarico
    % %
    if t < tDisturbo
        Fin = 9.4;
    else
        Fin = 2*9.4;
    end

    % Fin = 9.4;
    % [y(1)] = livello serbatoio 1
    % [y(2)] = livello serbatoio 2

    dy(1,:) = 1/A1*(Fin - (y(1)-y(2))/R1);
    dy(2,:) = 1/A2*((y(1)-y(2))/R1 - coeffScarico*y(2));

end
```



How to



```
function dy = ODELivelloSerbatoioControlloP(t,y)

    global R1 A1 A2 livelloSetPoint Kc tDisturbo
    coeffScarico h0
    epsi = y(2) - livelloSetPoint ;

    if t < tDisturbo
        Fin = 9.4;
        Fout = coeffScarico*y(2);
    else
        Fin = 2*9.4;
        Fin_ss = 9.4;
        % VM = Fout
    Fout = Fin_ss + Kc*epsi;
    end

    % [y(1)] = livello serbatoio 1
    % [y(2)] = livello serbatoio 2
    dy(1,:) = 1/A1*( Fin - (y(1)-y(2))/R1);
    dy(2,:) = 1/A2*((y(1)-y(2))/R1 - Fout);
end
```




How to



```
function dy = ODELivelloSerbatoiControlloPI(t,y)

    global R1 A1 A2 livelloSetPoint Kc tDisturbo
    coeffScarico h0 tau_I
    % [y(1)] = livello serbatoio 1
    % [y(2)] = livello serbatoio 2
    % [y(3)] = Integrale di epsi in dt
    epsi = y(2) - livelloSetPoint ;
    if t < tDisturbo
        Fin = 9.4;
        Fout = coeffScarico*y(2);
    else
        Fin = 2*9.4;
        % VM = Fout ( portata uscente dal secondo serbatoio)
        Fout = 9.4 + Kc*epsi + Kc/tau_I *y(3);
    end
    dy(1,:) = 1/A1*( Fin - (y(1)-y(2))/R1);
    dy(2,:) = 1/A2*((y(1)-y(2))/R1 - Fout);
    dy(3,:) = epsi;
end
```